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IN THE CLAIMS:

This listing of claims will replace all prior versions and listings of claims in the application.

- 1. (original) A method of time varying filtering, comprising:
- a. filtering a segment of a signal using a filter; and
- disengaging the filter in a sequence of graduated steps at the end of the segment;
 - c. repeating steps a and b until all segments have been filtered.
- 2. (currently amended) The method of claim 1, where a given the filter is disengaged by changing the coefficients from their regular values for the filter to values reflecting a gain of unity and no phase delay.
 - 3. (canceled)
- 4. (currently amended) The method of claim 3 2, where in each said step the filter has a different set of coefficients.
- 5. (currently amended) The method of claim 4, where one sample from the input signal is processed during each step.
- 6. (currently amended) The method of claim 4, where two or more samples from the input signal are processed during each step.
 - 7. (currently amended) A method of time varying filtering, comprising:
- a. engaging a filter in a sequence of graduated steps at the beginning of a signal segment;

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- b. filtering the segment of the signal using the filter; and
- c. repeating steps a and b until all segments have been filtered.
- 8. (currently amended) The method of claim 7, where a given the filter is engaged by changing the coefficients from values reflecting a gain of unity and no phase delay to their regular values.
 - 9. (canceled)
- 10. (currently amended) The method of claim 9 8, where in each said step the filter has a different set of coefficients.
- 11. (currently amended) The method of claim 10, where one sample from the input signal is processed during each step.
- 12. (currently amended) The method of claim 10, where two or more samples from the input signal are processed during each step.
 - 13. (currently amended) A method of time varying filtering, comprising:
- a. engaging a filter in a sequence of graduated steps at the beginning of a signal segment;
 - b. filtering the segment of the signal using the filter;
- c. disengaging the filter in a sequence of graduated steps at the end of a signal segment; and
 - d. repeating steps a-c until all segments have been filtered.
- 14. (currently amended) The method of claim 13, where a given the filter is engaged by changing the coefficients from values reflecting a gain of unity and no phase delay to their regular values.

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15. (canceled)

- 16. (currently amended) The method of claim 15 14, where in each said step the filter has a different set of coefficients.
- 17. (currently amended) The method of claim 16, where one sample from the input signal is processed during each step.
- 18. (currently amended) The method of claim 16, where two or more samples from the input signal are processed during each step.
- 19. (original) An article comprising a computer readable medium having instructions stored thereon which when executed causes:
 - a. filtering a segment of a signal using a filter;
- b. disengaging the filter in a sequence of graduated steps at the end of the segment; and
 - c. repeating steps a and b until all input signal segments have been filtered.
- 20. (original) An article comprising a computer readable medium having instructions stored thereon which when executed causes:
- a. engaging a filter in a sequence of graduated steps at the beginning of a signal segment;
 - b. filtering the segment using the filter; and
 - c. repeating steps a and b until all input signal segments have been filtered.
- 21. (original) An article comprising a computer readable medium having instructions stored thereon which when executed causes:
 - a. filtering a segment of a signal using a filter;

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- b. disengaging the filter in a sequence of graduated steps at the end of the segment;
- c. engaging a filter in a sequence of graduated steps at the beginning of the next segment of the signal; and
 - d. repeating steps a-c until all input signal segments have been filtered.
 - 22. (original) A method, comprising:

inaudibly switching one or more filters on and/or off during processing of an input signal by:

migrating their coefficients from an original set of values to a final set of values through a series of intermediate steps.

23. (original) The method of claim 22, where said filters are:

engaged by changing the coefficients to their regular values for the filter from values reflecting a gain of unity and no phase delay, and

disengaged by changing the coefficients from their regular values for the filter to values reflecting a gain of unity and no phase delay.

- 24. (original) The method of claim 23, where each filter is disengaged or disengaged, as the case may be, in a number of intermediate steps.
- 25. (original) The method of claim 24, where in each said step the filter has a different set of coefficients.
- 26. (original) The method of claim 25, where one sample from the input signal is processed during each step.
- 27. (original) The method of claim 25, where two or more samples from the input signal are processed during each step.

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28-29. (canceled)

- 30. (currently amended) The method of any of claims 1-6 1, 2, 4-6, or of claims 13-18 13, 14, 16-18, where a filter is disengaged by the disengaging includes:
 migrating its the filter's poles to its zeros, or its zeros to its poles.
 - 31. (currently amended) The method of claim 30, where <u>further comprising:</u> removing the filter after the migration has been completed, the filter is removed.
- 32. (currently amended) The method of claim 30, where after the migration has been eempleted, further comprising:

moving the colocational poles and zeros are then migrated to the origin via a series of intermediate steps after the migrating has been completed.

33. (currently amended) The method of claim 30, where after the migration has been completed: further comprising:

moving the colocational poles and zeros are then migrated to the origin via a series of intermediate steps after the migrating has been completed; and

removing the filter is then removed after the moving.